## **Application Form for Mechatronics Option in Mechanical Engineering**

Mechatronics is an integrated approach to mechanical, electronic and computer engineering for the design of "smart" products and "intelligent" manufacturing systems. The option normally begins in second year but may be started later. Students <u>must have completed at least 35 credit hours</u> in the BScE (ME) program before acceptance into the Option. More information can be found on the ME website (www.unbf.ca/eng/ME).

Student name:		Student no.:	Credit hrs completed:
Student signat	ure:	)ate:	_Start term (3 or 5):
	:: n to accommodate you in the co ing courses required for the Me		s, <u>indicate when</u> you plan to
Course no.	Course name	Academic term	Calendar year
ECE 2214	Digital Logic Design	Fall	
ECE 2215	Digital Logic Design Lab	Fall	
ECE 2711	Electric Circuits	Fall	
ECE 3111	Electronics I	Fall	
ME 4673	Introduction to Mechatronics	Winter	
ME 4683	Mechatronics Applications	Fall	
Indicate which	oice of technical electives is rep of the following you are now co		
Course no.			
	Course na	ne	Indicate interest
ECE 3221	Computer Organization (4 ch)		Indicate interest
ECE 3221 ECE 4323	Computer Organization (4 ch) Industrial Control Systems (4 ch)		Indicate interest
ECE 3221 ECE 4323 ECE 4333	Computer Organization (4 ch) Industrial Control Systems (4 c Robotics (4 ch)		Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343	Computer Organization (4 ch) Industrial Control Systems (4 c Robotics (4 ch) Haptic Robotics (4 ch)	ch)	Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343 ECE 4923	Computer Organization (4 ch) Industrial Control Systems (4 c Robotics (4 ch) Haptic Robotics (4 ch) Introduction to Biomedical Eng	ch)	Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343 ECE 4923 ME 4173	Computer Organization (4 ch) Industrial Control Systems (4 ch) Robotics (4 ch) Haptic Robotics (4 ch) Introduction to Biomedical Englished Robot Kinematics (4 ch)	ch) gineering (4 ch)	Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343 ECE 4923 ME 4173 ME 4703	Computer Organization (4 ch) Industrial Control Systems (4 ch) Robotics (4 ch) Haptic Robotics (4 ch) Introduction to Biomedical Eng Robot Kinematics (4 ch) Mechanical Engineering Meas	ch) gineering (4 ch) urements (4 ch)	Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343 ECE 4923 ME 4173 ME 4703 ME 5183	Computer Organization (4 ch) Industrial Control Systems (4 ch) Robotics (4 ch) Haptic Robotics (4 ch) Introduction to Biomedical Eng Robot Kinematics (4 ch) Mechanical Engineering Meas Industrial Robotics and Autom	ch) gineering (4 ch) urements (4 ch)	Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343 ECE 4923 ME 4173 ME 4703 ME 5183 ME 5643	Computer Organization (4 ch) Industrial Control Systems (4 ch) Robotics (4 ch) Haptic Robotics (4 ch) Introduction to Biomedical Eng Robot Kinematics (4 ch) Mechanical Engineering Meas Industrial Robotics and Autom Automatic Controls II (4 ch)	gineering (4 ch) urements (4 ch) ation (4 ch)	Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343 ECE 4923 ME 4173 ME 4703 ME 5183 ME 5643 ME 5653	Computer Organization (4 ch) Industrial Control Systems (4 ch) Robotics (4 ch) Haptic Robotics (4 ch) Introduction to Biomedical English Robot Kinematics (4 ch) Mechanical Engineering Meas Industrial Robotics and Autom Automatic Controls II (4 ch) Predictive Control and Intellige	urements (4 ch) ation (4 ch) ent Sensors (4 ch)	Indicate interest
ECE 3221 ECE 4323 ECE 4333 ECE 4343 ECE 4923 ME 4173 ME 4703 ME 5183 ME 5643 ME 5653 ME 5953 Other technica	Computer Organization (4 ch) Industrial Control Systems (4 ch) Robotics (4 ch) Haptic Robotics (4 ch) Introduction to Biomedical Eng Robot Kinematics (4 ch) Mechanical Engineering Meas Industrial Robotics and Autom Automatic Controls II (4 ch) Predictive Control and Intellige Embedded Flight Control Systems at elective courses may be seed Studies or the Option Co-ordinal	urements (4 ch) ation (4 ch) ent Sensors (4 ch) ems (4 ch)	